

# More Precision

wireSENSOR // Draw-wire displacement sensors



# Low-cost draw-wire sensors

# wire SENSOR MK120 analog

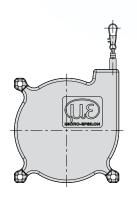
Robust plastic housing

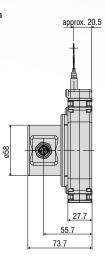
Customer-specific designs

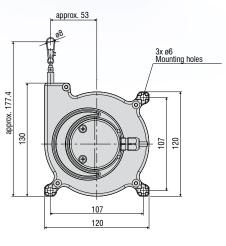
Potentiometer, current or voltage output



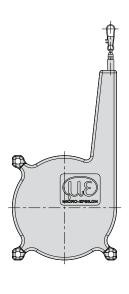


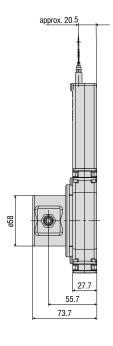


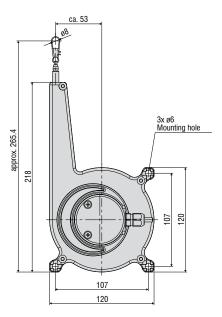




#### Measuring range 7500 mm



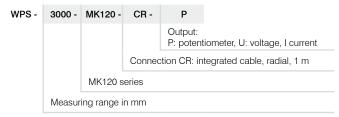




All dimensions in mm, not to scale

Model			WPS-3000-MK120	WPS-5000-MK120	WPS-7500-MK120	
Measuring range			3000 mm	5000 mm	7500 mm	
Analog output 1)			Potentiometer, current, voltage			
Resolution	Hybrid p	otentiometer P10	towards infinity			
Linearity	Hybrid potentiometer P10	≤ ±0.15% FSO	≤ ±4.5 mm	≤ ±7.5 mm	≤ ±11.25 mm	
Sensor eleme	ent			Hybrid potentiometer		
Wire extensio	n force (max.)			approx. 10 N		
Wire retraction	n force (min.)			approx. 4 N		
Wire accelera	tion (max.)		approx. 6 g			
Material		Housing	Plastics (PA 6)			
Material		Measuring wire	Polyamide-coated stainless steel (ø 0.45 mm)			
Wire mounting	g		Wire clip			
Installation			Mounting holes or mounting grooves on the sensor housing			
Temperature r	rango	Storage	-20 +80 °C			
iemperature i	ange	Operation	-20 +80 °C			
Connection		integrated cable, radial, length 1 m				
Shock (DIN EN 60068-2-27)		40 g / 6 ms in 3 axes, 2 directions and 3000 shocks each				
Vibration (DIN EN 60068-2-6)		3 g / 10 $\dots$ 5000 Hz in 3 axes and 10 cycles each				
Protection class (DIN EN 60529)			IP65			
Weight		approx. 850 g (incl. cable)				

### Article designation



FSO = Full Scale Output

1) Specifications for analog outputs from page 58 onwards.

# Options

## wireSENSOR

#### Customer-specific modifications for your series application

If the standard models do not meet certain specific requirements, draw-wire sensors from the standard range can be adapted accordingly by Micro-Epsilon. Cost-effective implementation can already be achieved with medium-sized quantities (depending on the type and number of changes).

## Measuring wire

- Plastics
- Stainless steel (coated/uncoated)
- Different diameters
- Thicker wire for improved snap protection

### - Wire clip - Eyelet - Thread - Wire extension

Wire attachment





- Adaption of supply voltage
- Inverted signal
- Redundant signal outputs
- Alignment cable/connector outlet



### Sensor mounting

- Mounting bracket
- Mounting plate
- Magnetic holder

### Wire guide

- Wire wiper
- Different designs of integrated deflection pulleys
- Wire outlet socket from ceramics for increased diagonal pull up to 15°



### Housing and environment

- Wire outlet right (standard) / left
- Protection class up to IP69K
- Drainage holes
- Stainless steel spring
- Housing material
- Wire acceleration
- Snap protection

<sup>\*</sup> Some options cannot be combined with each other; availability of options on request

## Accessories

## wireSENSOR

### Wire deflection pulleys for external installation

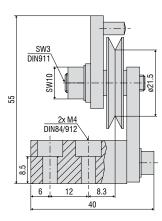
### TR1-WDS

Wire deflection pulley, adjustable, for sensors with a wire diameter  $\leq 0.45 \ \text{mm}$ 



cannot jump off!

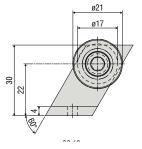
Set the distance so small that the wire

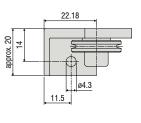


TR3-WDS

Wire deflection pulley, fixed, for sensors with a wire diameter  $\leq 0.45 \ \text{mm}$ 



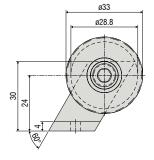


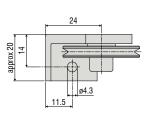


#### TR4-WD9

Wire deflection pulley, fixed, for sensors with a wire diameter of 0.8 mm to 1 mm





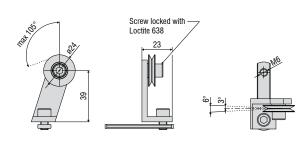


### Wire deflection pulley for direct installation on the sensor housing

#### TR5-WDS

Integrated wire deflection pulley for P115 sensors with a wire diameter of 0.45 mm



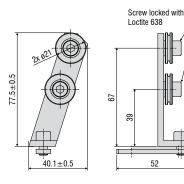


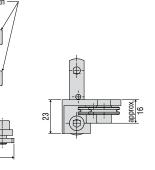
All dimensions in mm, not to scale

#### TR5-WDS(03)

Integrated double deflection pulley for P115 sensors with a wire diameter of 0.45 mm

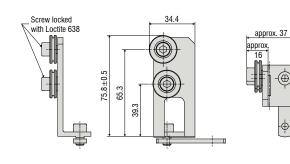






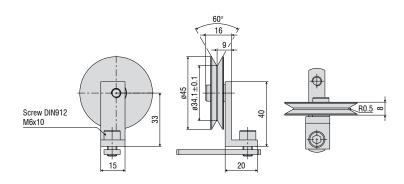
 $\begin{tabular}{l} \textbf{TR5-WDS(04)} \\ \textbf{Integrated double deflection pulley, } 90^\circ \ angled, for P115 \ sensors \ with a wire diameter of 0.45 \ mm \end{tabular}$ 

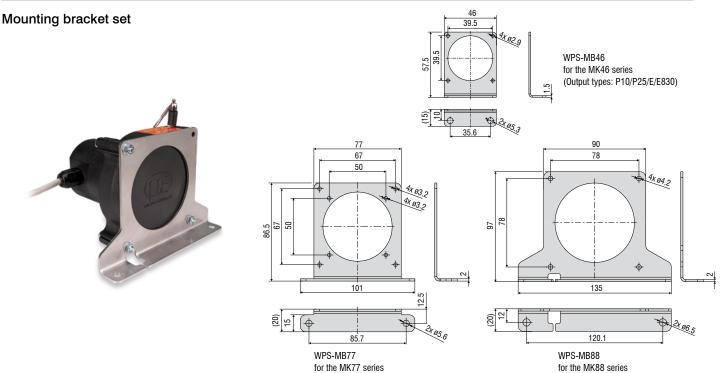




TR6-WDS(01)
Integrated wire deflection pulley for the P115 sensors with a wire diameter of 1 mm

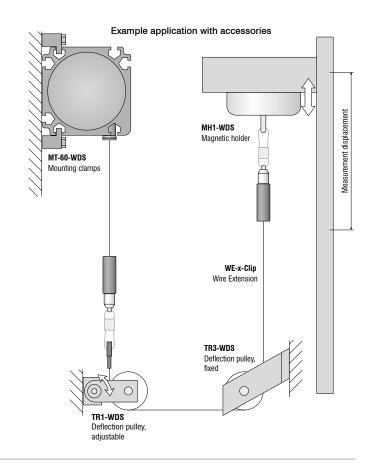






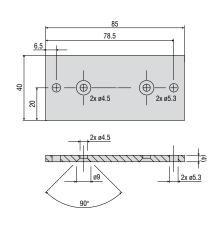
# Accessories & Notes for installation wireSENSOR

Accessories	
WE-xxx-M4	Wire extension with M4 wire connection, x=wire length
WE-xxxx-Clip	Wire extension with eyelet, x = wire length
WE-xxx-Clip-WSS	Wire extension with clip and uncoated wire d=0.45 mm
WE-xxxx-Ring-PW	Wire extension with plastic ring and para-aramid wire, 1 mm
GK1-WDS	Fork head for M4
MH1-WDS	Magnetic holder for wire attachment
MH2-WDS	Magnetic holder for sensor mounting
MT-60-WDS	Mounting clamps for WDS-P60
FC8	Mating plug for WDS straight, 8-pin
FC8/90	Mating plug, 90° angled for WDS
PC3/8-WDS	Sensor cable, 3 m long, for WDS with 8-pin cable connector
WDS-MP60	Mounting plate for P60 models
WPS-MB46	Mounting bracket set for the MK46 series (output type: P10/P25/E/E830)
WPS-MB77	Mounting bracket set for the MK77 series
WPS-MB88	Mounting bracket set for the MK88 series
PC2/10-WDS-A	Cable for SSI encoder, 2 m long
PC10/10-WDS-A	Cable for SSI encoder, 10 m long
PC5/5-IWT	Sensor cable, 5 m long, M12x1 connector, 5-pin, A-coding



#### WDS-MP60 Mounting plate for P60 models



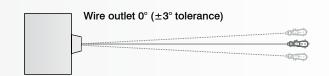


All dimensions in mm, not to scale

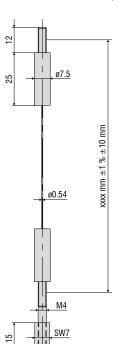
#### Installation instructions:

Wire attachment: during installation, do not allow at any time the measuring wire to freely return.

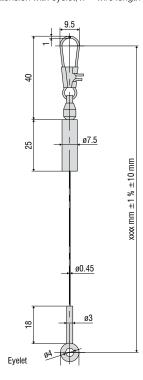
Angle of wire outlet: Make sure during installation that the wire outlet is straight (tolerance of  $\pm 3^{\circ}$ ). Exceeding this tolerance leads to increased wear of the wire material and on the wire outlet.



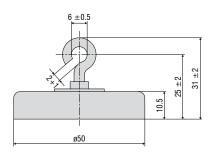
**WE-xxxx-M4**Wire extension with M4 wire connection, x=wire length



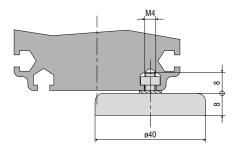
 $\label{eq:WE-xxxx-Clip} \mbox{Wire extension with eyelet, } \mbox{$x=$ wire length}$ 



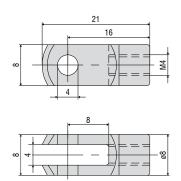
MH1-WDS Magnetic holder for wire attachment



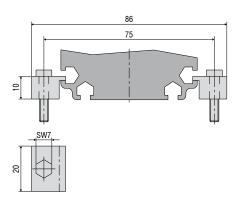
MH2-WDS Magnetic holder for sensor mounting



# **GK1-WDS**Fork head for M4



MT-60-WDS Mounting clamps for WDS-P60



# Output specifications wireSENSOR

# Analog

Output	Connector M16 -SA / -SR	Integrated cable -CA / -CR	Open contacts
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Potentiometer output (P)		12			
Input voltage Resistance Temperature coefficient	max. 32 VDC with 1 kOhm / max. 1 W 1 kOhm ±10 % (resistance divider) ±0.0025 % FSO/°C	5 0 4 3 8 0 1 7 1 6 Sensor side		2 - CW->	3881
		1 = Input + 2 = Ground 3 = Signal	White = Input + Brown = Ground Green = Signal	1 = Input + 2 = Signal 3 = Ground	CCW 1 CLOCKWISE CLOCKWISE

Voltage output (U)			
Supply voltage	14 27 VDC (non-stabilized)		
Current consumption	max. 30 mA	2	
Output voltage	0 10 VDC Option 0 5 / ±5 V	5 6 4	
Load resistance	>5 kOhm	7 6	
Output noise	0.5 mV <sub>eff</sub>	Sensor side	
Temperature coefficient	±0.005 % FSO/°C	Solidor dide	
Electromagnetic compatibility (EMC)	EN 61000-6-4 EN 61000-6-2		
Adjustment range (if supported by the model)		1 = Power supply	White = Supply
Zero	±20 % FSO	2 = Ground 3 = Signal	Brown = Ground Green = Signal
Sensitivity	±20 %	4 = Ground	Yellow = Ground

Current output (I)				
Supply voltage	14 27 VDC (non-stabilized)			
Current consumption	max. 35 mA			
Output current	4 20 mA	2		
Load	<600 Ohm	5 • • 4		
Output noise	$<$ 1.6 $\mu$ A <sub>eff</sub>			
Temperature coefficient	±0.01 % FSO/°C	7 6		
Electromagnetic compatibility (EMC)	EN 61000-6-4 EN 61000-6-2	Sensor side		
Adjustment range (if su	pported by the model)			
Zero	< ±18 % FSO	1 = Power supply	White = Supply	
Sensitivity	±15 %	2 = Ground	Brown = Ground	

# CANopen

(for the MK88 and K100 series)

CANopen features		
Profiles	Communication profile CiA 301. Device profile CiA 406 (absolute linear encoder)	
SDO	1x SDO server	
PDO	2x TxPDO	
PDO modes	Event/time-triggered, synchronous (cyclic/acyclic)	
Preset value	The "Preset" parameter can be used to set the current measured value to any value. The difference from the original value is stored in the object.	
Direction	Via the operating parameter, the counting direction of the measured values can be reversed	
Diagnosis	Heartbeat, Emergency Message	
Default setting	AutoBaud(9), Node-ID 1	

Setting the baud rate		
Baud rate adjustable via	LSS or object 0x3001	
0	1000 kBaud	
2	500 kBaud	
3	250 kBaud	
4	125 kBaud	
6	50 kBaud	
9	AutoBaud (default)	

Description of the connections		
Pin	Assignment	
1	n. c.	
2	V+ (732VDC)	
3	GND	
4	CAN-High	
5	CAN-Low	



### Setting the subscriber address (node ID)

Address adjustable via LSS or object 0x3000 (1....127, 1=default)

# Output specifications

# wireSENSOR

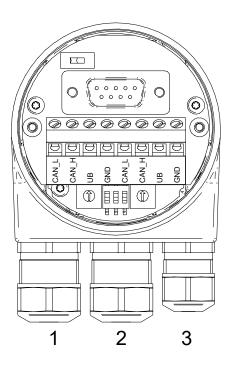
# CANopen

(for P60, P96, P115 and P200 series)



Setting the CANopen baud rate				
Baud rate	DIP switch setting			
Daud rate	1	2	3	
10 kBit/s	OFF	OFF	OFF	
20 kBit/s	OFF	OFF	ON	
50 kBit/s	OFF	ON	OFF	
125 kBit/s	OFF	ON	ON	
250 kBit/s	ON	OFF	OFF (factory settings)	
500 kBit/s	ON	OFF	ON	
800 kBit/s	ON	ON	OFF	
1 MBit/s	ON	ON	ON	

If Node-ID 00 is set, the baud rate can be programmed via the CAN bus.



Description of the CANopen connections		
GND	Ground connection for UB	
UB	Operating voltage	
CAN_H	CAN bus signal (dominant High)	
CAN_L	CAN bus signal (dominant Low)	

Max. core cross-section			
Single-wire (rigid)	1.5 mm 2		
Fine-wired (flexible)	1.0 mm2		
Fine-wired (flexible)	With ferrule 0.75 mm2		

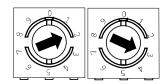
Cable diameter		
Cable gland 1,2	ø810 mm (-40+85 °C) ø59 mm (-25+85 °C)	
Cable gland 3	Ø4.56 mm (-40+85 °C) Ø36 mm (-25+85 °C)	

#### Tightening torque

Terminal block/screw terminal max. 0.4 Nm (recommended tightening torque 0.3 Nm)

### Settings of the CANopen participant address

Address can be set with rotary switch. Example: Participant address 23

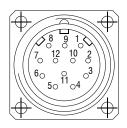


# SSI (Gray Code)

# Pin assignment Flange socket M23, 12-pin, pin contacts, CW (assignment according to option 3252)

PIN	Assignment
1	+Vs
2	0 V
3	Clock+
4	Data+
5	SET
6	Data-
7	Clock-
8	-
9	DIR
10	-
11	-
12	-

Connections		
SET	Zero setting input For setting a zero point at any point. The zeroing process is triggered by a High pulse and must take place after the rotating direction selection (DIR). Pulse duration > 100 ms. For maximum interference immunity, connect to 0 V after zeroing.	
DIR	Counting direction input When not connected, this input is on High. DIR High means increasing output data with a clockwise rotating shaft when looking at the flange. DIR Low means increasing values with a counterclockwise rotating shaft when looking at the flange. For maximum interference immunity, connect to +Vs or 0 V depending on the direction of rotation.	



Switching level		
SSI switch		
SSI clock	RS422 with terminating resistance 120 $\Omega$	
SSI data RS422		
Control inputs of input circuit		
Input level High	>0.7 UB	
Input level Low	<0.3 UB	
Input resistance	10 kΩ	

# Output specifications

# wireSENSOR

## **PROFIBUS**

Profibus DP features		
Bus protocol	Profibus-DPV0	
Device profile	Device class 1 and 2	
Cyclical data exchange	Communication in accordance with DPV0	
Input data	Position value Additional configurable speed signal	
Output data	Preset value	
Preset value	This parameter can be used to set the rotary encoder to a desired position value that corresponds to a defined axis position of the system. The storage is non-volatile.	
Rotary direction	This parameter can be used to parameterize the direction of rotation in which the position value should rise or fall.	
Scaling	Parameterization of the steps per rotation and the total resolution.	
Gear factor	Adjustable via counter / denominator	
Diagnosis	Position and parameter errors Monitoring multi-turn scanning Readable hour meter	

////	Terminal  O O O O O O O O O O O O O O O O O O O	Participant address
1	2	3
	Cable gland	

Cable: 1, 2 =  $\emptyset$ 8 - 10 mm (-40 - 85 °C) /  $\emptyset$ 5 - 9 mm (-25 - 85 °C) Cable: 3 =  $\emptyset$ 4.5 - 6 mm (-40 - 85 °C) /  $\emptyset$ 3 - 6 mm (-25 - 85 °C)

Pin assignment			
+Vs	Operating voltage 830 VDC		
0 V	Ground connection related to +Vs		
А	Negative data line		
В	Positive data line		

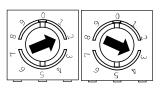
Terminals with the same designation are internally connected and functionally identical These internal terminal connections Vs-Vs / 0V-0V may be loaded with max. 1 A each

#### Terminator



Both ON = last participant Both OFF = participant X Default setting OFF

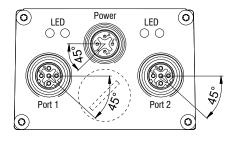
### Participant address



Adjustable via rotary switch Example: Participant address 23 Default setting. 00

# **PROFINET**

PROFINET features		
Bus protocol	PROFINET IO	
Device profile	Encoder Profile PNO 3.162 V4.1 and V3.1 PROFIdrive Profil PNO 3.172 V4.1	
Real-time classes	Realtime (RT) Class 1, IRT Class 3	
Transmission frequency	RT: 1 ms, 2 ms, 4 ms IRT: 250 \( \mu \text{s}, 500 \( \mu \text{s}, 1 \text{ ms}, 2 \text{ ms}, 4 \text{ ms} \)	
Update time	Min. 500 μs	
Product features	<ul> <li>- 100 MBaud Fast Ethernet</li> <li>- Device replacement without removable media</li> <li>- Media redundancy protocol MRP</li> <li>- Gear factor / round axis</li> </ul>	
Process data	<ul> <li>Position value 32-Bit input data with/without rotational speed 16 or 32 Bit</li> <li>Telegram 81-83 of the PROFIdrive profile</li> </ul>	
LED status display	Link/Activity, Status, Error	



Pin Assignment		
Operating voltage		
Pin	Connection	Description
1	UB	Operating voltage
2	n.c.	Do not connect
3	GND	Ground connection
4	n.c.	Do not connect



1x flange connector M12 (pin), A-coded

PROFINET (data line)		
Pin	Connection	Description
1	TxD+	Transmitted data+
2	RxD+	Received data+
3	TxD-	Transmitted data-
4	RxD-	Received data-

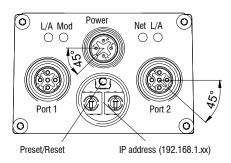


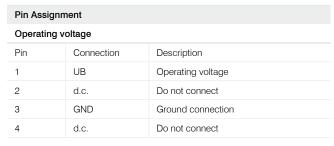
2x flange connector M12 (socket), D-coded

# Output specifications wireSENSOR

# EtherNet/IP

EtherNet/IP characteristics		
Bus protocol	EtherNet/IP	
Device profile	CIP Nov 2016, 22 <sub>hex</sub> Encoder	
Cycle time	1 ms	
Product features	Gear factor (round axis) and continuous operation     Plausibility test of adjustable parameters     Comprehensive diagnosis function     Adress Conflict Detection     Device Level Ring     Several simultaneous IO connections	
LED status display	2x Link/Activity, module status, network status	







1x flange connector M12 (pin), A-coded

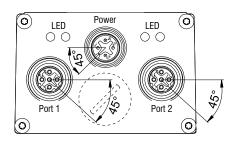
EtherNet/IP (data line)		
Pin	Connection	Description
1	TxD+	Transmitted data+
2	RxD+	Received data+
3	TxD-	Transmitted data-
4	RxD-	Received data-



2x flange connector M12 (socket), D-coded

# EtherCAT

EtherCAT characteristics	
Bus protocol	EtherCAT
Device profile	Encoder profile CANopen® CiA 406 Vers. 4.0.2 dated August 18, 2016
Operating modes	Free Run, synchronous with SM3 Event, DC Mode (Distributed Clocks)
Cycle time	Min. 62.5 μs
Product features	- Gear factor (round axis) and continuous operation - Time stamp (time of position data acquisition) - Plausibility check of adjustable parameters - Comprehensive diagnosis function - Preset gauge for position - File Access over EtherCAT (FoE)
Process data	<ul> <li>Position value 32-Bit input data</li> <li>with/without rotational speed 32 Bit</li> <li>Comprehensive process data mapping</li> </ul>
LED status display	2x Link/Activity, RUN, ERR



Pin Assignment		
Operating voltage		
Pin	Connection	Description
1	UB	Operating voltage
2	n.c.	Do not connect
3	GND	Ground connection
4	n.c.	Do not connect



1x flange connector M12 (pin), A-coded

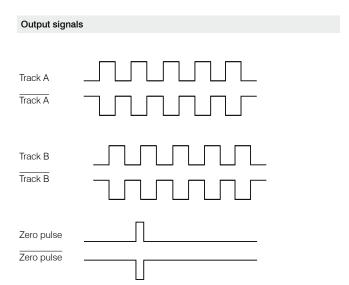
EtherCAT (data line)		
Pin	Connection	Description
1	TxD+	Transmitted data+
2	RxD+	Received data+
3	TxD-	Transmitted data-
4	RxD-	Received data-



2x flange connector M12 (socket), D-coded

# Output specifications wireSENSOR

# Incremental encoder



TTL Output	Line driver (5 VDC)
High level	≥ 2.5 V
Low level	≤ 0.5 V
High load	≤ 20 mA
Tracks	$A, \overline{A}, B, \overline{B}, O$

Output TTL01/ TTL02	NPN (5 VDC ±5 %)
High level	> 4.5 V
Low level	< 1.0 V
High load	≤ 3 mA
Tracks (TTL01)	A, B, 0
Tracks (TTL02)	$A, \overline{A}, B, \overline{B}, 0$

Output HTL	Push-pull (10 30 VDC)
High level	≥ V+ -3 V
Low level	≤ 1.5 V
High load	≤ 40 mA
Tracks	A, $\overline{A}$ , B, $\overline{B}$ , 0

Output E	Push-pull (5 VDC)
High level	≥ V+ -2.5 V
Low level	≤ 0.5 V
High load	≤ 50 mA
Tracks	A, B, 0

Output E830	Push-pull (8 30 VDC)
High level	≥ V+ -3 V
Low level	≤ 2.5 V
High load	≤ 50 mA
Tracks	A, B, 0

Pin assignment TTL, HTL		
Connector	Cable color	Assignment
Pin 1	pink	B-
Pin 2	-	-
Pin 3	blue	R+
Pin 4	red	R-
Pin 5	green	A+
Pin 6	yellow	A-
Pin 7	-	-
Pin 8	gray	B+
Pin 9	-	-
Pin 10	white	GND
Pin 11	-	-
Pin 12	brown	UB

Pin assignment E, E830	
Assignment	
0 V	
V+	
A	
Ā	
В	
B	
0	

Pin assignment TTL01		
Cable color	Assignment	
brown	0 V	
gray	V+	
white	A	
green	В	
yellow	0	

Pin assignment TTL02		
Cable color	Assignment	
red	V+	
black	0 V	
brown	A	
black	Ā	
orange	В	
black	B	
yellow	0	
black	n. c.	

## Sensors and Systems from Micro-Epsilon



Sensors and systems for displacement, distance and position



Sensors and measurement devices for non-contact temperature measurement



Measuring and inspection systems for metal strips, plastics and rubber



Optical micrometers and fiber optics, measuring and test amplifiers



Color recognition sensors, LED analyzers and inline color spectrometers



3D measurement technology for dimensional testing and surface inspection